



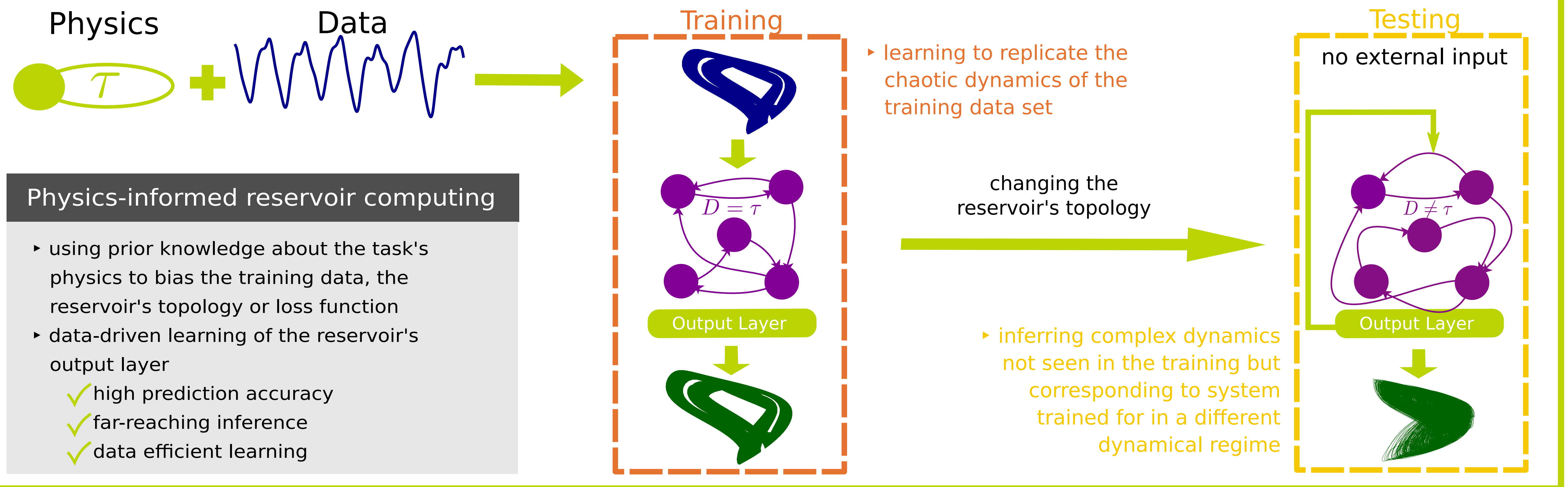
Inferring untrained complex dynamics of delay systems using a physics-informed reservoir

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Abstract



Model

Goal: predict the dynamics of high-dimensional chaotic delay systems

Example: Mackey-Glass system

$$\dot{y}(t) = -0.1y(t) + \frac{0.2y(t-\tau)}{1-y^{10}(t-\tau)}$$

dynamics rely on long history function

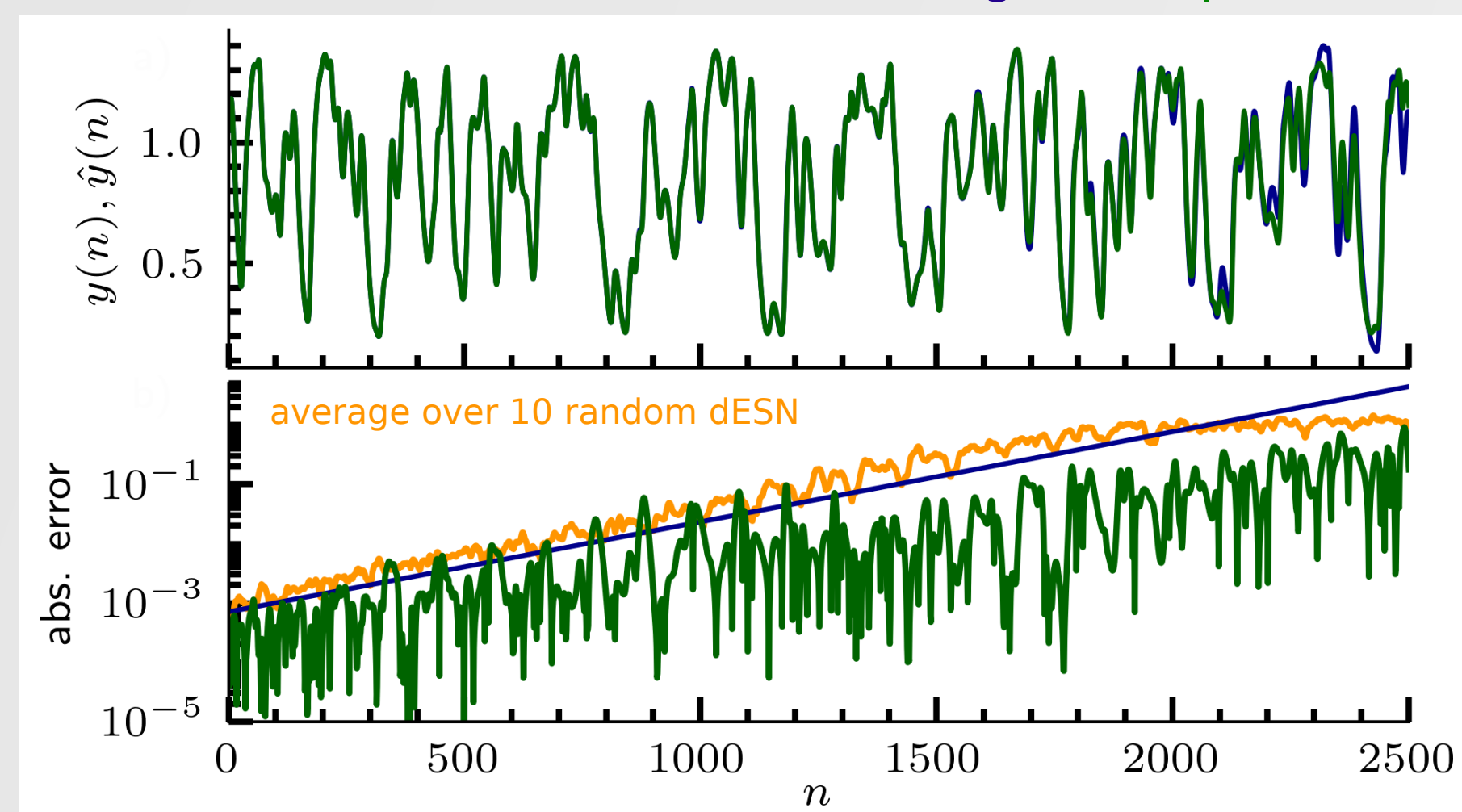
ML Model: delayed echo state network

$$\vec{x}(n+1) = \alpha\vec{x}(n) + \beta \tanh(\mathbf{W}\vec{x}(n-D) + \gamma\mathbf{W}_{in}s(n) + \mathbf{W}_b)$$

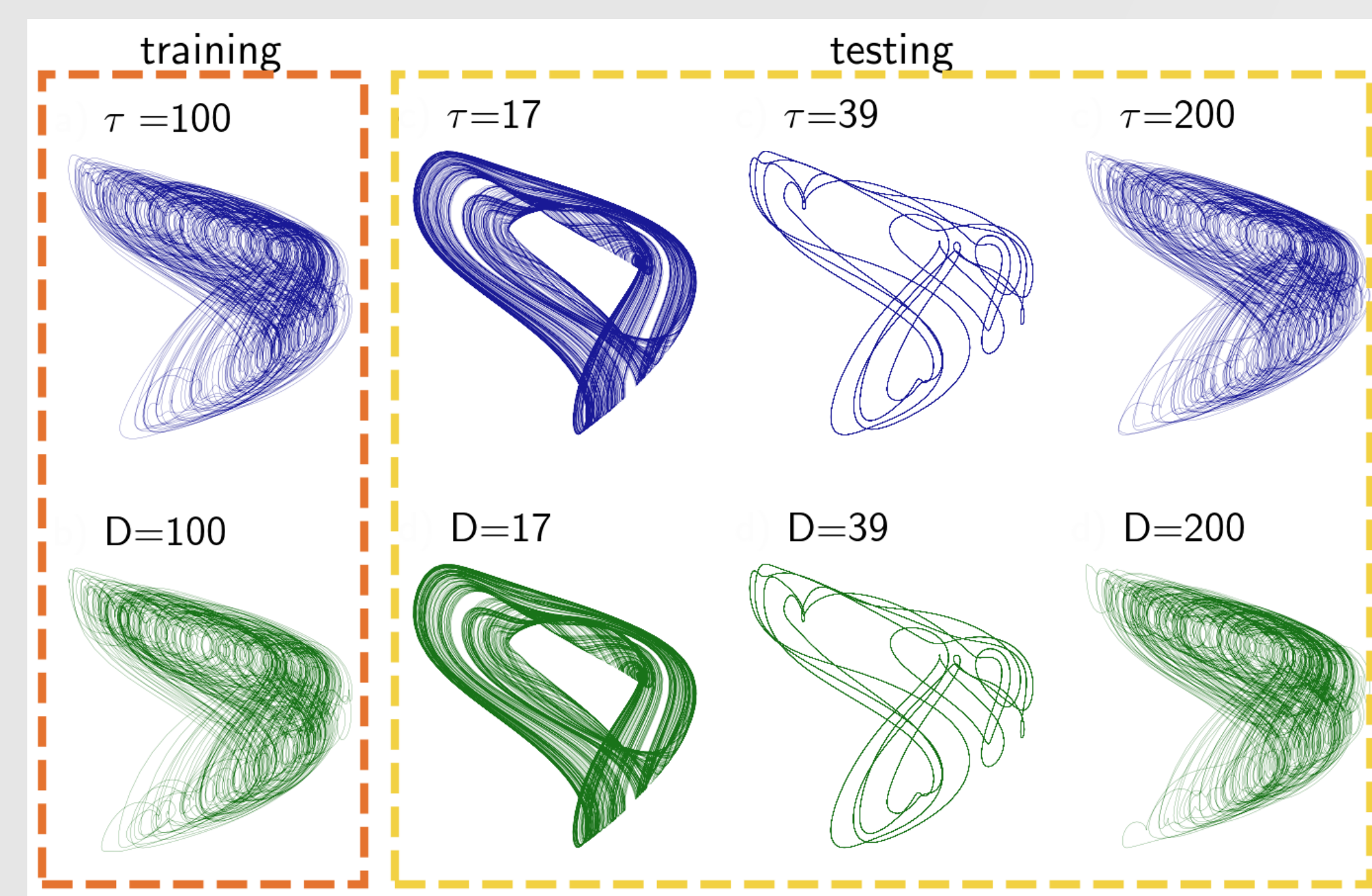
learn to predict time series one-step-ahead $\hat{y}(n) = W_{out}x(n)$

feed back prediction as new input \rightarrow autonomous running reservoir

autonomous continuation MG100 (original vs prediction)



Infer Different Dynamical Regimes

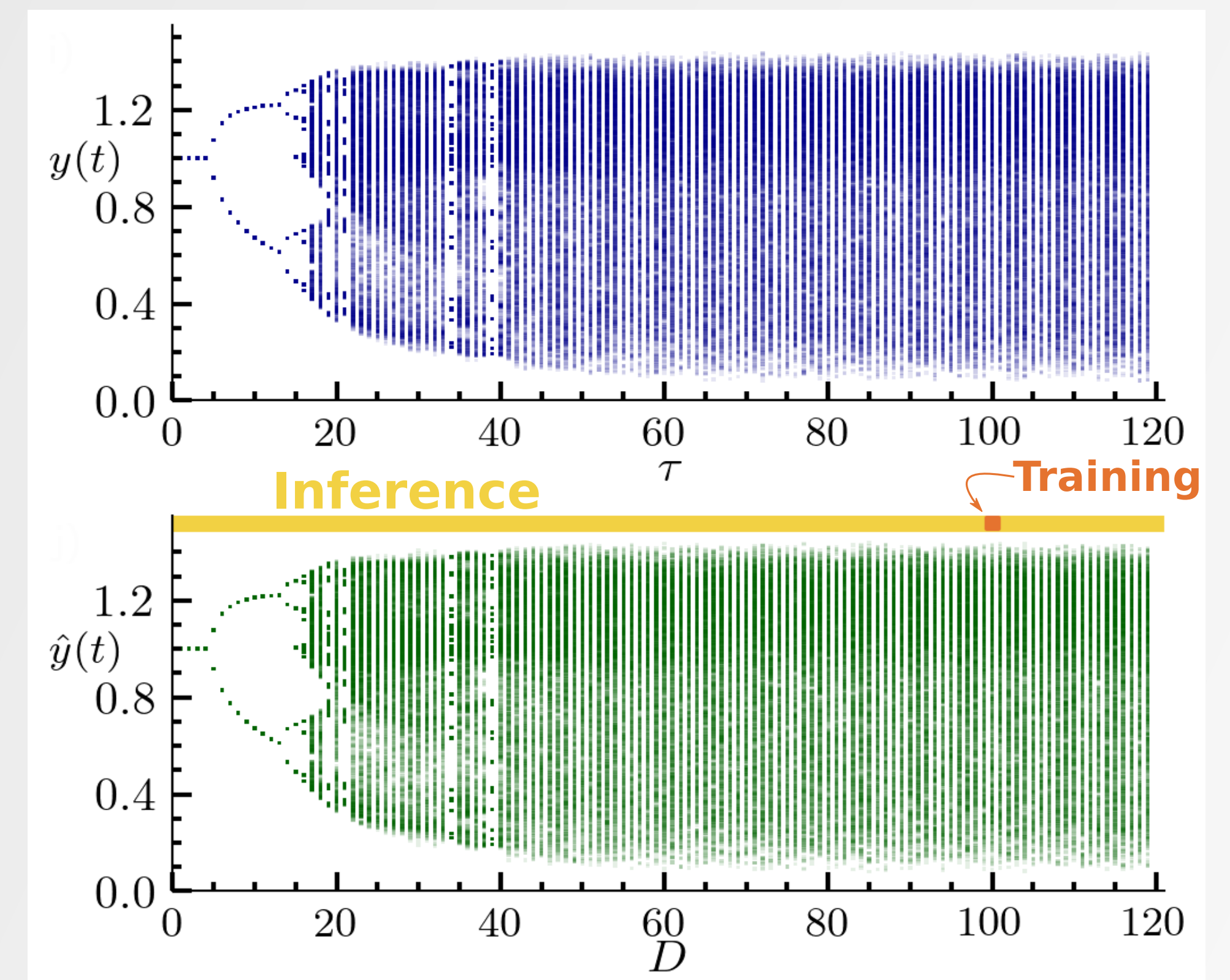


- prediction reveals bifurcations towards:
 - limit cycles
 - fixed points
- trained reservoir can infer unseen multistabilities
- learning from a single example enables to infer the entire bifurcation diagram of the delay system

after replicating the training data, changing the delay of the dESN

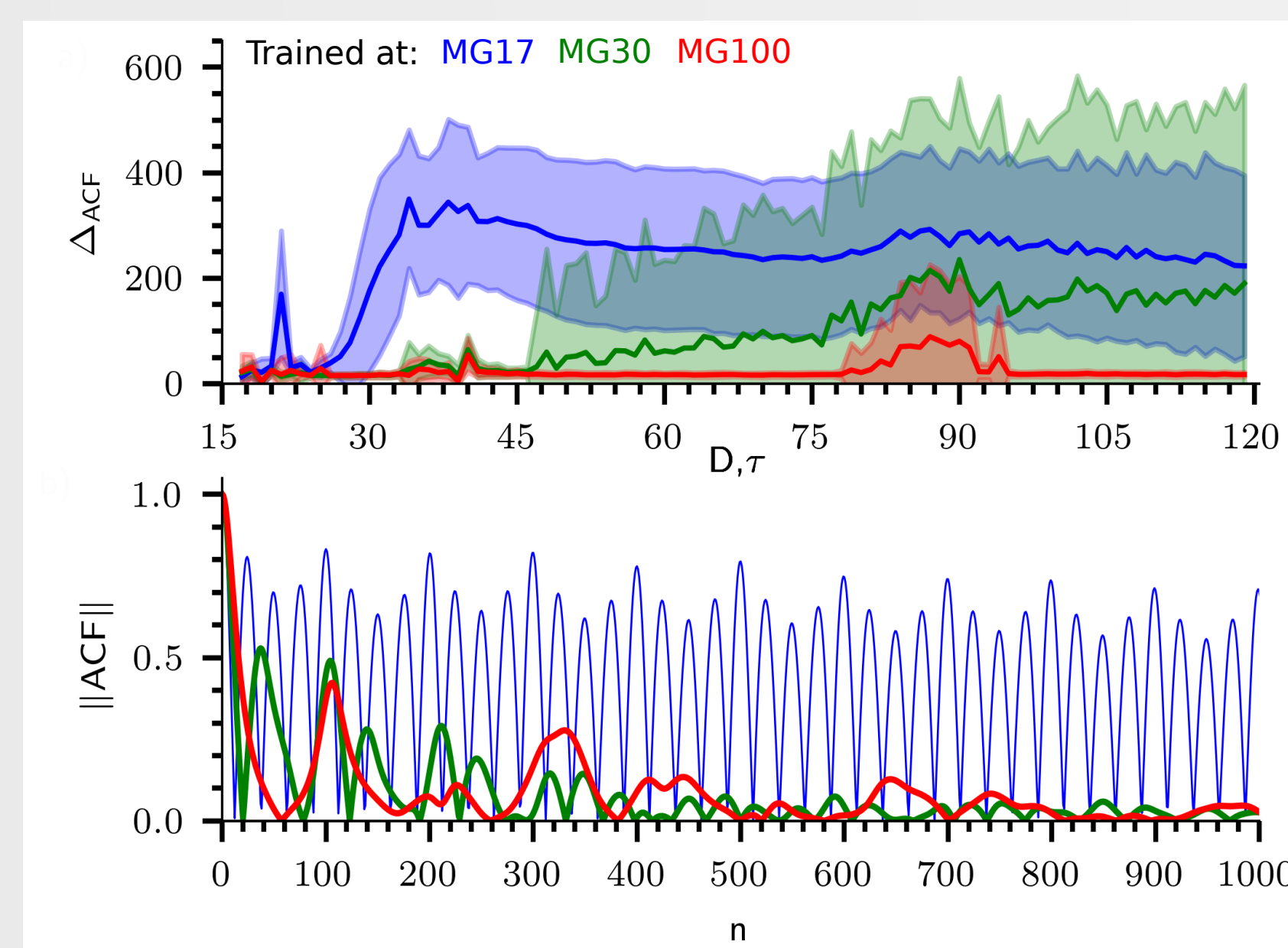
reservoir infers dynamics of the Mackey-Glass system with different delays

- output layer left unchanged
- no further training needed



What are the limitations?

- more complexity in the training data improves the inference ability
- e.g. learning from a chaotic system with a long delay enables to predict dynamics of systems with respectively shorter delay
- learning in the long delay limit enables prediction of much longer delays up to $\tau = 1000$



Conclusion & Outlook

- training a physics-informed reservoir on data enables prediction of dynamical features not seen during the training
- building digital twins of real world systems to infer dynamics of regimes where data is not accessible
- possible extension to other dynamical system such as:
 - delay-coupled oscillators
 - spatio-temporal systems

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