Oceanic three-dimensional Lagrangian Coherent Structures: A study in the Benguela upwelling region.

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Abstract

We study three dimensional oceanic Lagrangian Coherent Structures (LCSs) in the Benguela region, as obtained from an output of the ROMS model. To this end we first compute Finite-Size Lyapunov exponent (FSLE) fields in the region volume, characterizing mesoscale stirring and mixing there. Average FSLE values show a general decreasing trend with depth, but there is a local maximum at about 100m depth. LCSs are extracted as ridges of the calculated FSLE fields. They present a “curtain-like” geometry in which the strongest attracting and repelling structures appear as quasivertical surfaces. LCSs around a particular cyclonic eddy, pinched off from the upwelling front are also calculated. The LCSs are confirmed to provide pathways and barriers to transport in and out of the eddy.

Keywords: Lagrangian Coherent Structures, Finite-Size Lyapunov exponents, ocean transport, Benguela upwelling region, oceanic eddy

1. Introduction.

Mixing and transport processes are fundamental to determine the physical, chemical and biological properties of the oceans. From plankton dynamics to the evolution of pollutant spills, there is a wide range of practical issues that benefit from a correct understanding and modeling of these processes. Although mixing and transport in the oceans occur in a wide range of scales, mesoscale and sub-mesoscale variability are known to play a very important role (Thomas et al., 2008; Klein and Lapeyre, 2009).

Mesoscale eddies are especially important in this aspect because of their long life in oceanic flows, and their stirring and mixing properties. In the southern Benguela, for instance, cyclonic eddies shed from the Agulhas current can transport and exchange warm waters from the Indian Ocean to the South Atlantic (Byrne et al., 1995; Lehahn et al., 2011). On the other hand, mesoscale eddies have been shown to drive important biogeochemical processes in the ocean such as the vertical flux of nutrients into the euphotic zone (McGillicuddy et al., 1998; Oshchies and Garçon, 1998). Another effect of these eddies seems to be the intensification of mesoscale and sub-mesoscale variability due to the filamentation process where strong tracer gradients are created by the stretching of tracers in the shear- and strain-dominated regions in between eddy cores (Elhmaïdi et al., 1993).

In the last decades new developments in the description and modelling of oceanic mixing and transport from a Lagrangian viewpoint have emerged (Mariano et al., 2002; Lacasce, 2008). These Lagrangian approaches have been more frequently used due to the increased availability of detailed knowledge of the velocity field from Lagrangian drifters, satellite measurements and computer models. In particular, the very relevant concept of Lagrangian Coherent Structure (LCS) (Haller, 2000; Haller and Yuan, 2000) is becoming crucial for the analysis of transport in flows. LCSs are structures that separate regions of the flow with different dynamical behavior. They give a general geometric view of the dynamics, acting as a (time-dependent) roadmap for the flow. They are templates serving as proxies to, for instance, barriers and avenues to transport or eddy boundaries (Boffetta et al., 2001; Haller and Yuan, 2000; Haller, 2002; d’Ovidio et al., 2004, 2009; Mancho et al., 2006).

The relevance of the threedimensional structure of LCSs begins to be unveiled in atmospheric contexts (du Toit and Marsden, 2010; Tang et al., 2011; Tallapragada et al., 2011). In the case of oceanic flows, however, the identification of the LCSs and the study of their role on biogeochemical tracers transport has been mostly restricted to the marine surface (d’Ovidio et al., 2004; Waugh et al., 2006; d’Ovidio et al., 2009; Beron-Vera et al., 2008). This is mainly due to two reasons: a) tracer vertical displacement is usually very small with respect to the horizontal one; and b) satellite data of any quantity (temperature, chlorophyll, altimetry for velocity, etc.) are only available from the observation of the ocean surface. There are, however, areas in the ocean where vertical motions are fundamental. These are the so-called upwelling regions, which are the most biologically

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active marine zones in the world (Rossi et al., 2008; Pauly and Christensen, 1995). The reason is that due to an Ekman pumping mechanism close to the coast, there is a surface upwelling of deep cold waters rich in nutrients, inducing a high proliferation of plankton concentration. Typically, vertical velocities in upwelling regions are much larger than in open ocean, but still one order of magnitude smaller than horizontal velocities. Thus, it turns out crucial the identification of the three-dimensional (3d) LCSs in these areas, and the understanding of their correlations with biological activity. Another reason to include the third dimension in LCS studies is the vertical variation in their properties.

This is the main objective of this paper: the characterization of 3d LCSs, extracted in an upwelling region. For this goal we use Finite-Size Lyapunov Exponents (FSLEs). FSLEs (Aurell et al., 1997; Artale et al., 1997) measure the separation rate of fluid particles between two given distance thresholds, and LCS are computed as the ridges of the FSLE field (d’Ovidio et al., 2004; Molcard et al., 2006; Haza et al., 2008; d’Ovidio et al., 2009; Poje et al., 2010; Haza et al., 2010). We will make emphasis in the numerical methodology since up to now FSLEs have only been computed for the marine surface (an exception is Özgökmen et al. (2011)), and will focus our study to the Benguela upwelling zone, and to a particular eddy very prominent in the area at the chosen temporal window. Since this is a first attempt to study 3d oceanic LCS, more general results (on Benguela and other upwelling regions) are left for future work.

To circumvent the lack of appropriate observational data in the vertical direction, we use velocity fields from a numerical simulation. They are from the ROMS model (see section 2 below) which are of high resolution and appropriate to study regional-medium scale basins. Following many previous studies (d’Ovidio et al., 2004; Molcard et al., 2006; d’Ovidio et al., 2009; Branicki and Wiggins, 2009) we translate, assuming them to be valid, the mathematical results for Finite-Time Lyapunov Exponents (FTLE) to FSLE. In particular, we assume LCS are identified with ridges (Haller, 2001), i.e., the local extrema of the FTLE field, and also we expect, in correspondence with the results in Shadden et al. (2005) and Lekien et al. (2007) for FTLEs, that the material flux through these LCS is small and that they are transported by the flow as quasi-material surfaces.

The paper is organized as follows: In section II we describe the data and methods. In section III we present our results. Section IV contains a discussion of the results and Section V summarizes our conclusions.

2. Data and Methods.

2.1. Velocity data set.

The Benguela ocean region is situated off the west coast of southern Africa. It is characterized by a vigorous coastal upwelling regime forced by equatorward winds, a substantial mesoscale activity of the upwelling front in the form of eddies and filaments, and also by the northward drift of Agulhas eddies. The velocity data set comes from a regional ocean model simulation of the Benguela Region (Le Vu et al., 2011). ROMS (Shchepetkin and McWilliams, 2003, 2005) is a split-explicit free-surface, topography following model. It solves the incompressible primitive equations using the Boussinesq and hydrostatic approximations. Potential temperature and salinity transport are included by coupling advection/diffusion schemes for these variables. The model was forced with climatological data. The data set area extends from 12°S to 35°S and from 4°E to 19°E (see Fig. 1). The velocity field $\mathbf{u} = (u, v, w)$ consists of two years of daily averaged zonal ($u$), meridional ($v$), and vertical ($w$) components, stored in a three-dimensional grid with an horizontal resolution of 1/12 degrees ~ 8 km, and 32 vertical terrain-following levels.

2.2. Finite-Size Lyapunov Exponents.

In order to study non-asymptotic dispersion processes such as stretching at finite scales and time intervals, the Finite Size Lyapunov Exponent (Aurell et al., 1997; Artale et al., 1997) is particularly well suited. It is defined as:

$$\lambda = \frac{1}{\tau} \log \frac{\delta_f}{\delta_0}, \quad (1)$$

where $\tau$ is the time it takes for the separation between two particles, initially $\delta_0$, to reach $\delta_f$. In addition to the dependence on the values of $\delta_0$ and $\delta_f$, the FSLE depends also on the initial position of the particles and on the time of deployment. Locations (i.e. initial positions) leading to high values of this Lyapunov field identify regions of strong separation between particles, i.e., regions that will exhibit strong stretching during evolution, that can be identified with the LCS (Boffetta et al., 2001; d’Ovidio et al., 2004; Joseph and Legras, 2002).
In principle, for computing FSLEs in three dimensions one just needs to extend the method of d’Ovidio et al. (2004), that is, one needs to compute the time that fluid particles initially separated by \( \delta_0 = [(\delta x_0)^2 + (\delta y_0)^2 + (\delta z_0)^2]^{1/2} \) need to reach a final distance of \( \delta_f = [(\delta x_f)^2 + (\delta y_f)^2 + (\delta z_f)^2]^{1/2} \). The main difficulty in doing this is that in the ocean vertical velocities (even in upwelling regions) are much smaller than the horizontal ones, and so do not contribute significantly to particle dispersion when compared to horizontal velocities (Özgökmen et al., 2011). By the time the horizontal particle dispersion has scales of tens of hundreds of kilometers (typical mesoscale structures are studied using \( \delta_f \approx 100 \text{km} \) (d’Ovidio et al., 2004)), particle dispersion in the vertical can have at most scales of hundreds of meters and usually less. Thus, in this paper we implemented a quasi two-dimensional computation of FSLEs. That is, we make the computation for every (2d) ocean layer, but where the particle trajectories calculation use the full 3d velocity field.

More in detail, a grid of initial locations \( x_0 \) in the longitude/latitude/depth geographical space \((\phi, \theta, z)\), fixing the spatial resolution of the FSLE field, is set up at time \( t \). The horizontal distance among the grid points, \( \delta_0 \), was set to \( 1/36 \text{ degrees} \) (\( \approx 3 \text{ km} \)), i.e. three times finer resolution than the velocity field (Hernandez-Carrasco et al., 2011), and the vertical resolution (distance between layers) was set to 20 m. Particles are released from each grid point and their threedimensional trajectories calculated. The distances of each particle with respect to the ones that were initially neighbors at an horizontal distance \( \delta_0 \) are monitored until one of the horizontal separations reaches a value \( \delta_f \). By integrating the three dimensional particle trajectories backward and forward in time, we obtain the two different types of FSLE maps: the attracting LCS (for the backward), and the repelling LCS (forward) (d’Ovidio et al., 2004; Joseph and Legras, 2002). We obtain in this way a FSLE field with a horizontal spatial resolution given by \( \delta_0 \). The final distance \( \delta_f \) was set to 100 km, which is, as already mentioned, a typical length scale for mesoscale studies. The trajectories were integrated for a maximum of \( T = 178 \text{ days} \) (approximately six months) using an integration time step of 6 hours. When a particle reached the coast or left the velocity field domain, the FSLE value at its initial position and initial time was set to zero. If the particle trajectory horizontal separation remains smaller than \( \delta_f \) during all the integration time, then the FSLE for that location is also set to zero.

The equations of motion that describe the evolution of particle trajectories are

\[
\frac{d\phi}{dt} = \frac{1}{R_{c}} \cos(\theta) u(\phi, \theta, z, t),
\]

\[
\frac{d\theta}{dt} = \frac{1}{R_{c}} v(\phi, \theta, z, t),
\]

\[
\frac{dz}{dt} = w(\phi, \theta, z, t),
\]

where \( \phi \) is longitude, \( \theta \) is latitude and \( z \) is the depth. \( R_{c} \) is the radial coordinate of the moving particle \( R_{c} = R - z \), with \( R \approx 6371 \text{ km} \) the mean Earth radius. For all practical purposes, \( R_{c} \approx R \). Particle trajectories are integrated using a 4th order Runge-Kutta method. For the calculations, one needs the (3d) velocity values at the current location of the particle. Since the six grid nodes surrounding the particle do not form a regular cube, direct trilinear interpolation can not be used. Thus, an isoparametric element formulation is used to map the nodes of the velocity grid surrounding the particles position to a regular cube, and an inverse isoparametric mapping scheme (Yuan et al., 1994) is used to find the coordinates of the interpolation point in the regular cube coordinate system.

2.3. Lagrangian Coherent Structures.

In 2d, LCS practically coincide with (finite-time) stable and unstable manifolds of relevant hyperbolic structures in the flow (Haller, 2000; Haller and Yuan, 2000; Joseph and Legras, 2002). The structure of these last objects in 3d is generally much more complex than in 2d (Haller, 2001; Pouransari et al., 2010), and they can be locally either lines or surfaces. As commented before, however, vertical motions in the ocean are slow. Thus, at each fluid parcel the strongest attracting and repelling directions should be nearly horizontal. This and the incompressibility property implies that the most attracting and repelling regions (i.e. the LCSs) should appear as almost vertical surfaces. Then, the LCSs will have a “curtain-like” geometry, and will repel or attract the neighboring fluid along their transverse horizontal directions. We expect the LCS sheet-like objects to coincide with the strongest hyperbolic manifolds when these are twodimensional, and to contain the strongest hyperbolic lines.

The curtain-like geometry of the LCS was already commented in references such as Branicki and Malek-Madani (2010), Branicki and Kirwan (2010), or Branicki et al. (2011). In the last paper it was shown that, in a 3d flow, these structures would appear mostly vertical when the ratio of vertical shear of the horizontal velocity components to the average horizontal velocities is small. This ratio also determines the vertical extension of the structures. In Branicki and Kirwan (2010), the argument was used to construct a 3d picture of hyperbolic structures from the computation in a 2d slice. In the present paper we confirm the curtain-like geometry of the LCSs, and show that they are relevant to organize the fluid flow in this realistic 3d oceanic setting.

At difference with 2d where LCS can be visually identified as the maxima of the FSLE field, in 3d the ridges are hidden within the volume data. Thus, one needs to explicitly compute and extract them, using the definition of LCSs as the ridges of the FSLEs. A ridge \( L \) is a co-dimension 1 orientable, differentiable manifold (which means that for a three-dimensional domain \( D \), ridges are surfaces) satisfying the following conditions:

1. The field \( \lambda \) attains a local extremum at \( L \).
2. The direction perpendicular to the ridge is the direction of fastest descent of \( \lambda \) at \( L \).

Mathematically, the two previous requirements can be expressed as

\[
n^T \nabla \lambda = 0,
\]

\[
n^T H_n = \min_{|\delta=1} u^T H u < 0,
\]
where $\nabla \lambda$ is the gradient of the FSLE field $\lambda$, $n$ is the unit normal vector to $L$ and $H$ is the Hessian matrix of $\lambda$.

The method used to extract the ridges from the scalar field $\lambda(x_0, t)$ is from Schultz et al. (2010). It uses an earlier (Eberly et al., 1994) definition of ridge in the context of image analysis, as a generalized local maxima of scalar fields. For a scalar field $f : \mathbb{R}^n \to \mathbb{R}$ with gradient $g = \nabla f$ and hessian $H$, a $d$-dimensional height ridge is given by the conditions

$$\nabla_{d \leq n} g^T e_i = 0 \text{ and } \alpha_i < 0,$$

(7)

where $\alpha_i, i \in \{1, 2, \ldots, n\}$, are the eigenvalues of $H$, ordered such that $\alpha_1 \geq \ldots \geq \alpha_n$, and $e_i$ is the eigenvector of $H$ associated with $\alpha_i$. For $n = 3$, (7) becomes

$$g^T e_1 = 0 \text{ and } \alpha_3 < 0.$$

(8)

This ridge definition is equivalent to the one given by (5) since the unit normal $n$ is the eigenvector (when normalized) associated with the minimum eigenvalue of $H$. In other words, in $\mathbb{R}^3$ the $e_1$, $e_2$ eigenvectors point locally along the ridge and the $e_3$ eigenvector is orthogonal to it.

The ridges extracted from the backward FSLE map approximate the attracting LCS, and the ridges extracted from the forward FSLE map approximate the repelling LCS. The attracting ones are the more interesting from a physical point of view (d’Ovidio et al., 2004, 2009), since particles (or any passive scalar driven by the flow) typically approach them and spread along them, giving rise to filament formation. In the extraction process it is necessary to specify a threshold $s$ for the ridge strength $|\alpha_3|$, so that ridge points whose value of $\alpha_3$ is lower (in absolute value) than $s$ are discarded from the extraction process. Since the ridges are constructed by triangulations of the set of extracted ridge points, the $s$ threshold greatly determines the size and shape of the extracted ridge, by filtering out regions of the ridge that have low strength. The reader is referred to Schultz et al. (2010) for details about the ridge extraction method. The height ridge definition has been used to extract LCS from FTLE fields in several works (see, among others, Sadlo and Peikert (2007)).

3. Results

3.1. Three dimensional FSLE field

The three dimensional FSLE field was calculated for a 30 day period starting September 17, with snapshots taken every 2 days. The fields were calculated for an area of the Benguela ocean region between latitudes 20°S and 30°S and longitudes 8°E to 16°E (see figure 1). The area is bounded at NW by the Walvis Ridge and the continental slope approximately bisects the region from NW to SE. The western half of the domain has abyssal depths of about 4000 m. The calculation domain extended vertically from 20 up to 580 m of depth. Both backward and forward calculations were made in order to extract the attracting and repelling LCS.

Figure 2 displays the vertical profile of the average FSLE for the 30 day period. There are small differences between the backward and the forward values due to the different intervals of time involved in their calculation. But both profiles have a similar shape and show a general decrease with depth. There is a notable peak in the profiles at about 100 m depth that indicates increased mesoscale variability (and transport, as shown in Sect. 3.2 at that depth).

A snapshot of the attracting LCSs for day 1 of the calculation period is shown in figure 3. As expected, the structures appear as thin vertical curtains, most of them extending throughout the depth of the calculation domain. The area is populated with LCS, denoting the intense mesoscale activity in the Benguela region. As already mentioned, in three dimensions the ridges are not easily seen, since they are hidden in the volume data. However, the horizontal slices of the field in figure 3 show that the attracting LCS fall on the maximum backward FSLE field lines of the 2d slices. The repelling LCS (not shown) also fall on the maximum forward FSLE field lines of the 2d slices.

Since the $\lambda$ value of a point on the ridge and the ridges strength $\alpha_3$ are only related through the expressions (7) and (8), the relationship between the two quantities is not direct. This creates a difficulty in choosing the appropriate strength threshold for the extraction process. A too small value of $s$ will result in very small LCS that appear to have little influence on the dynamics, while a greater value will result in only a partial rendering of the LCS, limiting the possibility of observing their real impact on the flow. Computations with several values of $s$ lead us to the optimum choice $s = 20 \text{day}^{-1} \text{m}^{-2}$, meaning that grid nodes with $\alpha_3 < -20 \text{day}^{-1} \text{m}^{-2}$ were filtered out from the LCS triangulation.

We have seen in this section how the ridges of the 3d FSLE field, the LCS, distribute in the Benguela ocean region. Their
ubiquity shows their impact on the transport and mixing properties. In the next section we concentrate on the properties of a single 3d mesoscale eddy.

3.2. Study of the dynamics of a relevant mesoscale eddy

Let us study a prominent cyclonic eddy observed in the data set. The trajectory of the center of the eddy was tracked and it is shown in figure 4. The eddy was apparently pinched off at the upwelling front. At day 1 of the FSLE calculation period, its center was located at latitude 24.8°S and longitude 10.6°E, leaving the continental slope, and having a diameter of approximately 100 km. One may ask: what is its vertical size? is it really a barrier, at any depth, for particle transport?

To properly answer these questions the eddy, in particular its frontiers, should be located. From the Eulerian point of view, it is commonly accepted that eddies are delimited by closed contours of vorticity and that the existence of strong vorticity gradients prevent the transport in an out of the eddy. Such transport may occur when the eddy is destroyed or undergoes strong interactions with other eddies (Provenzale, 1999). In a Lagrangian view point, however, an eddy can be defined as a region delimited by intersections and tangencies of LCS, whether in 2d or 3d space. The eddy itself is an elliptic structure (Haller and Yuan, 2000; Branicki and Kirwan, 2010; Branicki et al., 2011). In this Lagrangian view of an eddy, the transport inhibition to and from the eddy is now related to the existence of these transport barriers delimiting the eddy region, which are known to be quasi impermeable.

Using the first approach, i.e., the Eulerian view, the vertical distribution of the $Q$-criterium (Hunt et al., 1988; Jeong and Husain, 1995) was used to determine the vertical extension of the mesoscale eddy. The $Q$ criterium is a 3d version of the Okubo-Weiss criterium (Okubo, 1970; Weiss, 1991) and measures the relative strength of vorticity and straining. In this context, eddies are defined as regions with positive $Q$, with $Q$ the second invariant of the velocity gradient tensor

$$ Q = \frac{1}{2} (\|\Omega\|^2 - \|S\|^2), $$

(9)

where $\|\Omega\|^2 = tr(\Omega^2)$, $\|S\|^2 = tr(SS^T)$ and $\Omega$, $S$ are the anti-symmetric and symmetric components of $\nabla u$.

Using $Q = 0$ as the Eulerian eddy boundary, it can be seen from Fig. 5 that the eddy extends vertically down to, at least, 600 m.

Let us move to the Lagrangian description of eddies, which is much in the spirit of our study, and will allow us to study particle transport: eddies can be defined as the region bounded by intersecting or tangent repelling and attracting LCS (Branicki and Kirwan, 2010; Branicki et al., 2011). Using this criterion, and first looking at the surface located at 200 m depth, we see in Fig. 6 that certainly the Eulerian eddy seems to be located inside the area defined by several intersections and tangencies of the LCS. This eddy has an approximate diameter of 100 km. In the south-north direction there are two intersections that appear to be hyperbolic points (H1 and H2 in figure 6). In the West-East direction, the eddy is closed by a tangency at the western boundary, and an intersection of lines at the eastern boundary. The eddy core is devoid of high FSLE lines, indicating that weak stirring occurs inside (d’Ovidio et al., 2004). As additional Eulerian properties, we note that near or at the intersections H1 and H2 the $Q$-criterium indicates straining motions. In the case of H2, figure 5 (right panel) indicates high shear up to 200m depth.
Figure 5: Colormap of $Q$-criterium interpolated on to the FSLE grid. White contours have $Q = 0$. Day 1 of the 30 day FSLE calculation period. Left panel: Latitude 24.5° S; Right panel: Longitude 10.5° E. Colorbar values are $Q \times 10^{10} \text{s}^{-2}$.

Figure 6: $Q$-criterium map at 200 m depth together with patches of backward (blue) and forward (green) FSLE values. FSLE patches contain the highest 60% of FSLE values. Colorbar values are $Q \times 10^{10} \text{s}^{-2}$. The eddy we study is the clear region in between points H1 and H2.

In 3d, the eddy is also surrounded by a set of attracting and repelling LCS (figure 7), calculated as explained in Subsection 2.3. The lines identified in figure 6 are now seen to belong to the vertical of these surfaces.

Note that the vertical extent of these surfaces is in part determined by the strength parameter used in the LCS extraction process, so their true vertical extension is not clear from the
results presented here. On the south, the closure of the La-
grangian eddy boundary extends down to the maximum depth of the calculation domain, but moving northward it is seen that the LCS shorten their depth. Probably this does not mean that the eddy is shallower in the North, but rather that the LCS are losing strength (lower \( |\alpha_3| \)) and portions of it are filtered out by the extraction process. In any case, it is seen that as in two-dimensional calculations, the LCS delimiting the eddy do not perfectly coincide with its Eulerian boundary (Joseph and Legras, 2002), and we expect the Lagrangian view to be more relevant to address transport questions.

In the following we study fluid transport across the eddy boundary. Some previous results for Lagrangian eddies were obtained by Branicki and Kirwan (2010) and Branicki et al. (2011). Applying the methodology of lobe dynamics and the turnstile mechanism to eddies pinched off from the Loop Cur- rent, Branicki and Kirwan (2010) observed a net fluid entrain-
ment near the base of the eddy, and net detrainment near the surface, being fluid transport in and out of the eddy essentially confined to the boundary region. Let us see what happens in our setting.

We consider six sets of 1000 particles each, that were re-
leased at day 1 of the FSLE calculation period, and their trajec-
tories integrated by a fourth-order Runge-Kutta method with a integration time step of 6 hours. The sets of particles were re-
leased at depths of 50, 100, 200, 300, 400 and 500 m. In figure 8 we plot the particle sets together with the Lagrangian bound-
aries of the mesoscale eddy viewed in 3d. A top view is shown in figure 9. As expected, vertical displacements are small.

At day 3 (top left panel of figures 8 and 9) it can be seen that there is a differential rotation (generally cyclonic, i.e. clock-
wise) between the sets of particles at different depths. The shal-
lower sets rotate faster than the deeper ones. This differential rotation of the fluid particles could be viewed, in a Lagrangian perspective, as the fact that the attracting and repelling strength of the LCS that limit the eddy varies with depth. Note that the six sets of particles are released at the same time and at the same horizontal positions, and thereby their different behavior is due to the variations of the LCS properties along depth.

At day 13 the vortex starts to expel material trough filamen-
tation (Figs.8 and 9, top right panels). A fraction of the par-
ticles approach the southern boundaries of the eddy from the northeast. Those to the west of the repelling LCS (green) turn west and recirculate inside the eddy along the southern attract-
ing LCS (blue). Particles to the east of the repelling LCS turn east and leave the eddy forming a filament aligned with an attracting (blue) LCS. At longer times trajectories in the south of the eddy are influenced by additional structures associated to
a different southern eddy. At day 29 (bottom right panels) the same process is seen to have occurred in the northern boundary, with a filament of particles leaving the eddy along the northern attracting (blue) LCS. The filamentation seems to begin earlier at shallower waters than at deeper ones since the length of the expelled filament diminishes with depth. However all of the expelled filaments follow the same attracting LCS. Figure 10 shows the stages previous to filamentation in which the LCS structure, their tangencies and crossings, and the paths of the particle patches are more clearly seen. Note that the LCS do not form fully closed structures and the particles escape the eddy through their openings. The images suggest lobe-dynamics processes, but much higher precision in the LCS extraction would be needed to really see such details.

This filamentation event seems to be the only responsible for transport of material outside of the eddy, since the rest of the particles remained inside the eddy boundaries. To get a rough estimate of the amount expelled in the filamentation process we tracked the percentage of particles leaving a circle of diameter 200km centered on the eddy center. In Fig. 11 the time evolution of this percentage is shown for the particle sets released at different depths. The onset of filamentation is clearly visible around days 9-12 as a sudden increase in the percentage of particles leaving the eddy. The percentage is maximum for the particles located at 100m depth and decreases as the depth increases. At 400 and 500m depth there are no particles leaving the circle. There is a clear lag between the onset of filamentation between the different depths: the onset is simultaneous for the 40m and 100m depths but occurs later for larger depths.

4. Discussion.

The spatial average of FSLEs defines a measure of stirring and thus of mixing between the scales used for its computation. The larger the average, the larger the mixing activity (d’Ovidio et al., 2004). The general trend in the vertical profiles of the average FSLE (Fig. 3) shows a reduction of mesoscale mixing with depth. There is however a rather interesting peak in this average profile occurring at 100m, i.e. close to the thermocline. It could be related to submesoscale processes that occur alongside the mesoscale ones. Submesoscale is associated to filamentation (the thickness of filaments is of the order of 10 km or less), and we have seen that the filamentation and the associated transport intensity (Fig. 11) is higher at 100 meters.
depth. It is not clear at the moment what is the precise mechanism responsible for this increased activity at around 100 m depth, but we note that the intensity of shearing motions (see the Q plots in 5) is higher in the top 200 meters. Less intense filamentation could be caused by reduction of shear in depths larger than these values.

From an Eulerian perspective, it is thought that vortex filamentation occurs when the potential vorticity (PV) gradient aligns itself with the compressional axis of the velocity field, in strain coordinates (Louazel and Hua (2004); Lapeyre et al. (1999)). This alignment is accompanied by exponential growth of the PV gradient magnitude. The fact that the filamentation occurs along the attracting LCS seems to indicate that this exponential growth of the PV gradient magnitude occurs across the attracting LCS.

We have confirmed that the structure of the LCSs is “curtain-like”, so that the strongest attracting and repelling structures are quasivertical surfaces. Their vertical extension would depend on the physical transport properties, but it is also altered by the particular threshold parameter selected to extract the LCSs. The important point is that, as in 2d, we have seen that they act as pathways and barriers to transport, so that they provide a skeleton organizing the transport processes.

5. Conclusions

Three dimensional Lagrangian Coherent Structures were used to study stirring processes leading to dispersion and mixing at the mesoscale in the Benguela ocean region. We have computed 3d Finite Size Lyapunov Exponent fields, and LCSs were identified with the ridges these fields. LCSs appear as quasivertical surfaces, so that horizontal cuts of the FSLE fields gives already a quite accurate vision of the 3d FSLE distribution. Average FSLE values generally decrease with depth, but we find a local maximum, and thus enhanced stretching and dispersion, at about 100m depth.

We have also analyzed a prominent cyclonic eddy, pinched off the upwelling front and study the filamentation dynamics in 3d. Lagrangian boundaries of the eddy were made of intersections and tangencies of attracting and repelling LCS that apparently emanating from two hyperbolic locations North and South of the eddy. The LCS are seen to provide pathways and barriers organizing the transport processes and geometry. This pattern extends down up to the maximum depth were we calculated the FSLE fields (~ 600 m), but the exact shape of the
boundary is difficult to determine due to the decrease in ridge strength with depth. This caused some parts of the LCS not to be extracted. The inclusion of a variable strength parameter in the extraction process is an important step to be included in the future.

The filamentation dynamics, and thus the transport out of the eddy, showed time lags with increasing depth. This arises from the vertical variation of the flow field. However the filamentation occurred along all depths, indicating that in reality vertical sheets of material are expelled from these eddies.

Many more additional studies are needed to further clarify the details of the geometry of the LCSs, their relationships with finite-time hyperbolic manifolds and three-dimensional lobe dynamics, and specially their interplay with mesoscale and sub-mesoscale transport and mixing processes.

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References


