# Assessment of SMOS measurements of Arctic Sea Ice Concentration



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7th Data Assimilation and PPP Ice Verification Workshop / ESRIN, Rome 5-7 April 2016



- SMOS Mission and products
- Basic Concepts on Sea Ice
- Theoretical determination of indices
- Determination of empirical tie points values
- Inversion algorithm
- Results and comparison with other sources
- Advantages and drawbacks
- Conclusions
- SSS of the Arctic Ocean



#### Measuring salinity from space: SMOS





ESA SMOS mission:

- Earth Explorer launched on Nov. 2009
- L-band (1.4 GHz) synthetic aperture radiometer, with many incidence angles (0 to 68°), large swath and full-pol.
- Polar orbit: 6am/6pm, 3-day repeat
- Measures:
  - SSS on the ocean
  - SM on land
  - Cryospheric applications : Ice thickness, sea ice concentration,
    Sea Surface salinity in Arctic Ocean



Water mission



Basic Concepts on Sea Ice



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SSMI



AMSR-E on Nasa AQUA



AMSR-2 on JAXA GCOM-W1

- Using combination of TB at frequencies: 6, 19, 37, 89 GHz, H/V pol.
- More than 10 different algorithms : Bootstraap, Bristol, Nasa Team, ASI, OSISAF, etc. -> each one has PROS/CONS

Paper from Ivanova et al., 2015 -> good resume comparison of algorithms.

### **Ice concentration measurement**

#### Sea Ice Emissivity & Ice Concentration Algorithms



• Indices (combination of TBs ) are commonly used

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 Tie points : typical radiometric meas. for sea ice and open water -> Empirically obtained



Theoretical Models

 State of the Art models used to describe TB from ICE: Vant et al. , Cox and Weeks, Leppäranta & Manninen, Burke et al. -> even theoretical models are not much reliable for ice.





# Determination of indices: based on **theoretical** models

Theoretical Models
 Sensitivity of TB and indices to geophysical parameters
 based on theoretical models

Sensitivity	Sea Temp.	Sea surf. Salinity	Ice Temp	Ice salinity
TB sea	0.52 K/ºC	0.51 K/pss		
PD sea	0.26 K/ºC	0.21 K/pss		
AD sea	0.20 K/ºC	0.12 K/pss		
TB ice			0.85 K/ºC	1 K/psu
PD ice			0.66 K/ºC	0.35 K/psu
AD ice			0.35 K/ºC	0.25 K/psu

PD and AD have lower sensitivity to temperature and salinity changes

Better to use indices



#### Data set: SMOS

- SMOS L1B 503, transformed to BOA, outlier filtered, inter/extrapolated to all incidence angles
- Average of 3 days for each month in 2014
- EASE Northern Hemisphere grid, equal area projection, at 25Km



Algorithm validation: No in situ measurements. There is a data base, but from 2006 to 2009.

Comparison with OSI-SAF algorithm with SSMIs: uses 19 and 37GHz.





## Temporal stability in Sea region

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### SMOS Temporal stability of the TP

**MY ICE** 

CSIC

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mylun

SMOS





**SEA** 







#### Comparison between Theoretical and empirical Tie Points

Tie Points	Theoretical	SMOS empirical
PD ice + snow (winter & autumn)	25	20
AD ice + snow	8	10
PD sea	63	62
AD sea	44	42

#### Small differences, about 20% on Ice, less on Sea



Method 1: Direct linear inversion:

- $PD = c \cdot PD_{ice} + (1 c) \cdot PD_{sea}$
- $AD = c \cdot AD_{ice} + (1 c) \cdot AD_{sea}$

- Where c is ice concentration value
- PD\_ice/sea and AD\_ice/sea are empirical Tie Points: the most frequent value in 100% of SEA/ICE region -> widely used

**Method 2: Maximum Likelihood Estimation**, define a normal distribution and assume a linear combination between ICE and Water Tie Points, for the mean and Std Dev of the Tie Points -> **Efficient and unbiased**.

• 
$$\rho_{PD} = N(\mu, \sigma) = \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}} = N((cPD_{ice} + (1-c)PD_{sea}), \sqrt{c^2 \sigma_{PD_ice}^2 + (1-c)^2 \sigma_{PD_sea}^2})$$

**Inversion Algorithm** 

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• 
$$\rho_{AD} = N((cAD_{ice} + (1-c)AD_{sea}), \sqrt{c^2 \sigma_{AD_{ice}}^2 + (1-c)^2 \sigma_{AD_{sea}}^2})$$

• MLE $\rightarrow$  max  $L = \ln(\rho_{PD}(c)) + \ln(\rho_{AD}(c))$  to get ice conc (c).



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ICE region , due to different penetration

#### Main differences due to thin ice



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SMOS Sea Ice thickness







![](_page_18_Picture_0.jpeg)

- Comparison static vs dynamic tie point on ICE:
  - Static: 1 Tie-Points: averaged TB (Dec to May data) for all year data
  - Dynamic: 2 Tie-points:

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- Winter TP: averaged TB from Dec to May and applied from Oct to May
- Summer TP: averaged TB Jun to Sep and applied from Jun to Sep

![](_page_18_Figure_6.jpeg)

# Comprison of MLE vs linear and using AD/PD/Both

**Results and comparison** 

![](_page_19_Figure_1.jpeg)

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Larger AD vs ADPD diff -> when max extension of thin ice. AD is less sensitive to thin ice Best results (vs OSISAF):

- MLE (lower RMS and noise)
- Only with AD -> main diff. on thin ice

![](_page_19_Figure_6.jpeg)

### SMOS SIC best configuration: MLE (AD) + 2 TP

![](_page_20_Figure_2.jpeg)

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Man

SMOS

![](_page_20_Figure_3.jpeg)

![](_page_20_Figure_4.jpeg)

![](_page_20_Figure_5.jpeg)

![](_page_20_Figure_6.jpeg)

![](_page_20_Figure_7.jpeg)

# A priori Error: propagation error from MLE weighted by σAD\_sea, σAD\_ice & σTB

Jan 2014

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March 2014

Mai 2014

![](_page_21_Figure_5.jpeg)

July 2014

![](_page_21_Figure_7.jpeg)

August 2014

![](_page_21_Figure_9.jpeg)

![](_page_21_Figure_10.jpeg)

2

![](_page_22_Picture_0.jpeg)

![](_page_22_Figure_2.jpeg)

![](_page_23_Picture_0.jpeg)

#### **Quality of the retrieved SIC**

![](_page_23_Figure_2.jpeg)

![](_page_23_Figure_3.jpeg)

24

Both have similar ability to detect 100% sea Good performance in winter, during summer and autumn -> snow gets wet -> differences for the dynamic tie points of SAF algo, every 2 weeks

## Quality of the retrieved SIC

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![](_page_24_Figure_2.jpeg)

Algorithm used: MLE AD+2TP

2TP MLE AD 2n to 5th of Gen 2014 180°W 20°W 120°W 0.5 0.5 400 900 900 ရ ရ ရ 60°2 60°4 0 0 to 5th of Gen 201 AF>0.9 & S 0° 0° SMOS **OSISAF** 180°W 180°W 1200 1200 0.5 120°W 120°W SIC from SMOS vs OSISAI 0 0.5 600ч С С 60°h 60°4 -0.5 0 0° 0° **SMOS-OSISAF** SMOS + OSISAF mask

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![](_page_25_Picture_2.jpeg)

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![](_page_26_Figure_1.jpeg)

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SAF>0.9 & S

2TP MLE AD 2n to 5th of Mar 2014 20°W 0.5 400 900 900 60°4 0 0° SMOS

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![](_page_27_Figure_2.jpeg)

![](_page_27_Figure_3.jpeg)

![](_page_27_Figure_4.jpeg)

**SMOS-OSISAF** 

![](_page_27_Figure_6.jpeg)

SMOS + OSISAF mask

![](_page_27_Picture_8.jpeg)

![](_page_27_Figure_9.jpeg)

![](_page_28_Figure_1.jpeg)

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2TP MLE AD 2n to 5th of Mai 2014 180°W 120°W 20°W 0.5 0.5 400 900 900 ရ ရ ရ 60% 60% 0 0 0° 0° SMOS **OSISAF** 180°W 180°W 1200 1200 0.5 120°W 20°W 0 0.5 800ч С С 60°h 60°h -0.5 0 0° **0**°

SMOS + OSISAF mask

![](_page_29_Picture_3.jpeg)

**SMOS-OSISAF** 

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SIC from SMOS vs OSISAI

SAF>0.9 & S

![](_page_30_Figure_1.jpeg)

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2TP MLE AD 2n to 5th of Jul 2014 180°W 120°W 20°W 0.5 800<del>0</del> 60°4 60°h 0 0° SMOS 180°W 0.5 1200 20°W 120°W 0 500 60°h

0 0° **OSISAF** 180°W 1200 0.5 ୍କ ପୁର୍ଯ୍ଭ

0°

0.5

0

800

![](_page_31_Figure_3.jpeg)

![](_page_31_Figure_4.jpeg)

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![](_page_31_Figure_5.jpeg)

SMOS + OSISAF mask

![](_page_32_Figure_1.jpeg)

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2TP MLE AD 2n to 5th of Set 2014 180°W 20°W 120°W 0.5 0.5 800<del>0</del> 800 60°h Soon 0 0 2p to 5th of Set 201 0° 0° SMOS **OSISAF** 180°W 180°W 1200K 1200 0.5 120°W 120°W SIC from SMOS vs OSISAI 0 0.5 800ч С С 60°h 60°4 -0.5 0 0° 0° **SMOS-OSISAF** SMOS + OSISAF mask

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AF>0.9 & S

![](_page_34_Figure_1.jpeg)

![](_page_34_Picture_2.jpeg)

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AF>0.9 & S

0.5

0

0.5

0

to 5th of Nov 201

SIC from SMOS vs OSISAI

2TP MLE AD 2n to 5th of Nov 2014 180°W 20°W 20°W 0.5 400 900 900 ရ ရ ရ 60°2 60°h 0 0° 0° SMOS **OSISAF** 180°W 180°W 1200 0.5 1200 20°W 120°W 0 800-୍କ ପୁର୍ଯ୍ଭ 60°h 60°4 -0.5 0° 0°

SMOS + OSISAF mask

**SMOS-OSISAF** 

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![](_page_35_Picture_5.jpeg)

SAF>0.9 & S

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![](_page_36_Figure_1.jpeg)

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**Advantages and drawbacks** 

Main drawbacks of SMOS SIC:

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SMOS

- Underestimation on thin ice -> but detection of thin ice
- Lower spatial resolution (25km)
- Main problems of other SIC, from Ivanova et al. 2015 SMOS almost
  - Atmosphere correction: water vapour and cloud liq low ice concentration
    SMOS annot

![](_page_37_Figure_6.jpeg)

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**Advantages and drawbacks** 

Main drawbacks of SMOS SIC:

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SMOS

- Underestimation on thin ice -> but detection of thin ice
- Lower spatial resolution (25km)
- Main problems of other SIC, from Ivanova et al. 2015
  - Atmosphere correction: water vapour and cloud liq low ice concentration
  - Sensitivity wit SMOS is less sensitive
  - Snow cover thickness -> difficult to determine
  - Seasonal changes on ice tie points of up to 10K

![](_page_38_Figure_9.jpeg)

![](_page_38_Figure_10.jpeg)

**SMOS** almost

transparent

**SMOS not affected** 

by snow thickness

lal

![](_page_39_Picture_0.jpeg)

- AD and PD are robust indices to retrieve SIC, more independent to geophysical changes than TB. AD is less sensitive to ice thickness.
- MLE algorithm is better than linear -> less noisy.

**CONCLUSIONS** 

- SMOS leads to lower SIC than OSISAF on thin ice, due to its different penetration.
- Correlation is high between SMOS and OSISAF SICs.
- SMOS less sensitive to atmosphere and geophysical conditions.
- Need Data for validation (SAR/INSITU)

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Investigate how to retrieve simultaneously SIC and Sea Ice Thickness (SIT) by using both AD and PD indices from SMOS measurements

![](_page_40_Picture_0.jpeg)

# SSS at high latitudes

- For the Arctic Ocean, sea water density depends more on salinity than on temperature, and hence the thermohaline circulation mainly determined by salinity.
- An increased level of river discharge to the Arctic Ocean. -> the dynamical impact of such increase remains an enigma

![](_page_40_Figure_4.jpeg)

<u>http://cp34-bec.cmima.csic.es/</u> <- DATA HERE</p>

![](_page_41_Picture_0.jpeg)

### SSS at high latitudes

Remote sensing of the Arctic Ocean salinity by SMOS would provide an unprecedented source of information about the salinity and sea ice variability.

![](_page_41_Figure_3.jpeg)

**SSS** ->Norwegian fjords

SSS Hudson Bay

# Quality assessment: comparison with Argo

![](_page_42_Figure_1.jpeg)

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![](_page_42_Figure_2.jpeg)

	Mean	Std	RMS
2011	-0.05	0.32	0.35
2012	0.05	0.34	0.38
2013	0.04	0.25	0.29

43

![](_page_43_Picture_0.jpeg)

WOA13-TSG

EN4-TSG

#### **Comparison with transects**

![](_page_43_Figure_2.jpeg)

0.96

1.31

0.96

0.80

1.18

1.21

![](_page_44_Picture_0.jpeg)

# **Monitoring the Arctic rivers**

Machenzie

![](_page_44_Figure_3.jpeg)

![](_page_44_Figure_4.jpeg)

Monthly river discharge from http://rims.unh.edu

![](_page_44_Figure_6.jpeg)

Sea Surface Salinity

![](_page_44_Figure_8.jpeg)

![](_page_45_Picture_0.jpeg)

- SMOS is capable to measure Sea Surface salinity from cold waters with an accuracy aprox 0.35 psu with respect ARGO measurements.
- SMOS is a good tool to **monitor river discharges** in the Arctic Ocean.
- SMOS gives better accuracy SSS data than WOA13 climatology and EN4 datasets.
- Better corrections can be performed using sophisticated processing tools (work going on at BEC).

# Thank you for your attention

# Data in http://cp34-bec.cmima.csic.es/

![](_page_46_Picture_2.jpeg)

Distribution of measured PD and AD

#### **Histograms of measurements inside ROIs:**

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![](_page_47_Figure_2.jpeg)

PD & AD distributions are unimodal and symmetric -> can be approximated as Gaussian distributions

# Stability of TiePoints with time esa

![](_page_48_Figure_1.jpeg)

![](_page_48_Picture_2.jpeg)

25-29 May 2015 | ESA-ESAL | Villatranca (Madrid), Spain

→ 2nd SMOS

![](_page_49_Picture_0.jpeg)

![](_page_50_Picture_0.jpeg)

- PROS:
  - SMOS less sensitive to atmosphere
  - SMOS less sensitive to temperature / snow / wind
- CONS:
  - Lower spatial resolution
  - Underestimation on thin ice

However, synergy with high freq radiometres, region of thin ice (less than 70cm) can be masked

![](_page_51_Picture_0.jpeg)

# Stability of TiePoints with timeesa

![](_page_52_Figure_1.jpeg)

Mean\_PD\_FY~=mean\_PD\_MY Mean\_AD\_FY~=mean\_AD\_MY

Std\_PD\_FY~=2\*std\_PD\_MY Std\_AD\_FY~=2\*std\_AD\_MY

Could it be a proxy for FY/MY ice classification?

![](_page_52_Figure_5.jpeg)

![](_page_52_Picture_6.jpeg)

![](_page_53_Picture_0.jpeg)

### Theoretical models

![](_page_53_Figure_2.jpeg)

Differences:

- polarization differences
- TBV

- Sea ice dielectric constant: Vant et al (1978) + Cox & Weeks (1983) + Leppäranta & Manninen (1988)
- Seawater dielectric constant: Klein & Swift
- Ice over seawater: Burke et al. (1979) 3-layer model (snow+ice+water)
- Snow is transparent but effect on the incidence angle (Fresnel)

![](_page_54_Picture_0.jpeg)

#### **Theoretical behaviour of selected indices**

#### Polarization Difference Index: TBV - TBH

# Angular Difference Index: TBV for $\Delta \theta$ =35°

![](_page_54_Figure_4.jpeg)

![](_page_55_Picture_0.jpeg)

#### Identify ROIs for FY ice and MY ice

![](_page_55_Figure_2.jpeg)